Linearization and quadratization techniques for multilinear 0–1 optimization problems

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Multilinear 0–1 optimization

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$$\min \sum_{e \in E} a_e \prod_{i \in e} x_i + \sum_{i \in V} c_i x_i$$

s. t. $x_i \in \{0, 1\}$ $i \in V$

V = {1,...,n}, E = set of subsets e of V with |e| ≥ 2 and a_e ≠ 0,
V and E define a hypergraph H.

Example:

$$f(x_1, x_2, x_3) = 9x_1x_2x_3 + 8x_1x_2 - 6x_2x_3 + x_1 - 2x_2 + x_3$$

Applications: Computer Vision

Image restoration problems modelled as energy minimization

$$E(I) = \sum_{p \in \mathcal{P}} D_p(I_p) + \sum_{S \subseteq \mathcal{P}, |S| \ge 2} \sum_{p_1, \dots, p_s \in S} V_{p_1, \dots, p_s}(I_{p_1}, \dots, I_{p_s}),$$

where $l_p \in \{0, 1\} \ \forall p \in \mathcal{P}$.



(Image from "Corel database" with additive Gaussian noise.)

Applications

- Constraint Satisfaction Problem
- Data mining, classification, learning theory...
- Joint supply chain design and inventory management
- Production management

• ...

General idea



Standard Linearization (SL)

$$\min \sum_{e \in E} a_e \prod_{i \in e} x_i + \sum_{i \in V} c_i x_i$$

Standard Linearization (Fortet (1959), Glover and Woolsey (1973))

$$y_e = \prod_{i \in e} x_i$$

$$-y_e + x_i \ge 0 \qquad \forall i \in e, \forall e \in E \qquad (1)$$

$$y_e - \sum_{i \in e} x_i \ge 1 - |e| \qquad \forall e \in E \qquad (2)$$

SL main drawback and contributions

SL drawback: The continuous relaxation given by the SL is very weak!

Contributions:

- Characterization of cases for which SL provides a perfect formulation (Buchheim, Crama, Rodríguez-Heck (2017), discovered independently by Del Pia, Khajavirad (2017)).
- Definition of a class of valid inequalities strengthening the SL formulation, working especially well for simplified computer vision instances (Crama, Rodríguez-Heck (2017)).

General idea



Quadratizations definition

Definition: Quadratization

Given a multilinear polynomial f(x) on $\{0,1\}^n$, we say that g(x, y) is a **quadratization** of f if g(x, y) is a quadratic polynomial depending on x and on m auxiliary variables y_1, \ldots, y_m , such that

$$f(x) = \min\{g(x, y) : y \in \{0, 1\}^m\} \ \forall x \in \{0, 1\}^n.$$

Then,

 $\min\{f(x): x \in \{0,1\}^n\} = \min\{g(x,y): x \in \{0,1\}^n, y \in \{0,1\}^m\}.$

Which quadratizations are "good"?

- Small number of auxiliary variables.
- Good optimization properties: submodularity (intuitive measure: small number of positive quadratic terms).

Termwise quadratizations

Multilinear expression of a pseudo-Boolean function:

$$f(x) = -35x_1x_2x_3x_4x_5 + 50x_1x_2x_3x_4 - 10x_1x_2x_4x_5 + 5x_2x_3x_4 + 5x_4x_5 - 20x_1$$

Idea: quadratize monomial by monomial, using different sets of auxiliary variables for each monomial.

- Negative case well solved (one auxiliary variable, submodular quadratization).
- Positive monomials much more difficult: just improved the best bound for number of variables!

Negative monomial

Kolmogorov and Zabih (2004), Freedman and Drineas (2005).

$$-\prod_{i=1}^{n} x_{i} = \min_{y \in \{0,1\}} -y \left(\sum_{i=1}^{n} x_{i} - (n-1) \right)$$

Why is this a quadratization? $f(x) = -x_1x_2x_3x_4$

- If $x_i = 1$ for all *i*, then $\min_{y \in \{0,1\}} -y$, reached for y = 1, value -1.
- If there is an *i* with $x_i = 0$, then *y* has a nonnegative coefficient, minimum reached for y = 0.

Positive monomial: Literature

Ishikawa (2011)

$$\prod_{i=1}^{n} x_{i} = \min_{y_{1}, \dots, y_{k} \in \{0,1\}} \sum_{i=1}^{k} y_{i}(c_{i,n}(-S_{1}+2i)-1) + aS_{2},$$

 S_1, S_2 : elementary linear and quadratic symmetric polynomials in n variables,

$$\mathbf{k} = \lfloor \frac{\mathbf{n} - \mathbf{1}}{2} \rfloor$$
 and $c_{i,n} = \begin{cases} 1, ext{if } n ext{ is odd and } i = k, \\ 2, ext{otherwise.} \end{cases}$

- Number of variables: best published bound for positive monomials.
- Submodularity: ⁽ⁿ⁾₂ positive quadratic terms, but very good computational results.

1st improvement: $\lceil \frac{n}{4} \rceil$ variables

Theorem 1 (E. Boros, Y. Crama, E. R-H) For all integers n, m, if $n \ge 2$, $\frac{n}{4} \le m \le \frac{n}{2}$, and N = n - 2m then

$$g(x,y) = \frac{1}{2} (X - Ny_1 - 2Y) (X - Ny_1 - 2Y - 1)$$

is a quadratization of the positive monomial $P_n = \prod_{i=1}^n x_i$ using *m* auxiliary variables, where $X = \sum_{i=1}^n x_i$ and $Y = \sum_{j=2}^m y_j$.

2nd improvement: $\lceil log(n) \rceil - 1$ variables

Theorem 2 (E. Boros, Y. Crama, E. R-H)
Let
$$n \le 2^{k+1}$$
, $K = 2^{k+1} - n$ and $X = \sum_{i=1}^{n} x_i$. Then,
 $g(x, y) = \frac{1}{2}(K + X - \sum_{i=1}^{k} 2^i y_i)(K + X - \sum_{i=1}^{k} 2^i y_i - 1)$
is a quadratization of the positive monomial $f(x) = P_n(x) = \prod_{i=1}^{n} x_i$
using k auxiliary variables.

Proof idea:

- $g(x, y) \ge 0$ (half-product of consecutive integers).
- If $X \leq n-1$: K+X even: make 1st factor zero, K+X odd: make 2nd factor zero.
- If X = n: 1st factor is at least 2, 2nd factor is at least 1.

Positive monomial: new quadratizations

Smallest number of variables known until now:

• $\lceil log(n) \rceil - 1$ variables

Two other quadratizations, more variables but maybe better optimization properties (?)

- $\lceil log(n-1) \rceil$ variables.
- $\left\lceil \frac{n}{4} \right\rceil$ variables.

 \rightarrow Quadratizations being tested by a group at Cornell University.

Current work: computational

Instance sets:

- random polynomials,
- computer vision inspired polynomials,
- supply chain & inventory management.

Methods to compare:

- Standard linearization
- Termwise quadratizations

Pos. Mon. (P_n)	Neg. Mon. (<i>N_n</i>)
Ishikawa	1-var. quadrat.
$\left\lceil \frac{n}{4} \right\rceil$	1-var. quadrat.
$\lceil log(n-1) \rceil$	1-var. quadrat.
$\lceil log(n) \rceil - 1$	1-var. quadrat.

Current work: theoretical

Open questions:

Conjecture 1

We need at least $m = \lceil log(n) \rceil - 1$ variables to quadratize the positive monomial.

Conjecture 2

There is a trade-off between having small number of variables and good optimization properties, more precisely, the "most submodular" quadratizations of the positive monomial have n-1 positive quadratic terms and use m = n-2 variables.

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