Magnetocapillary self-assemblies: Swimming and micromanipulation

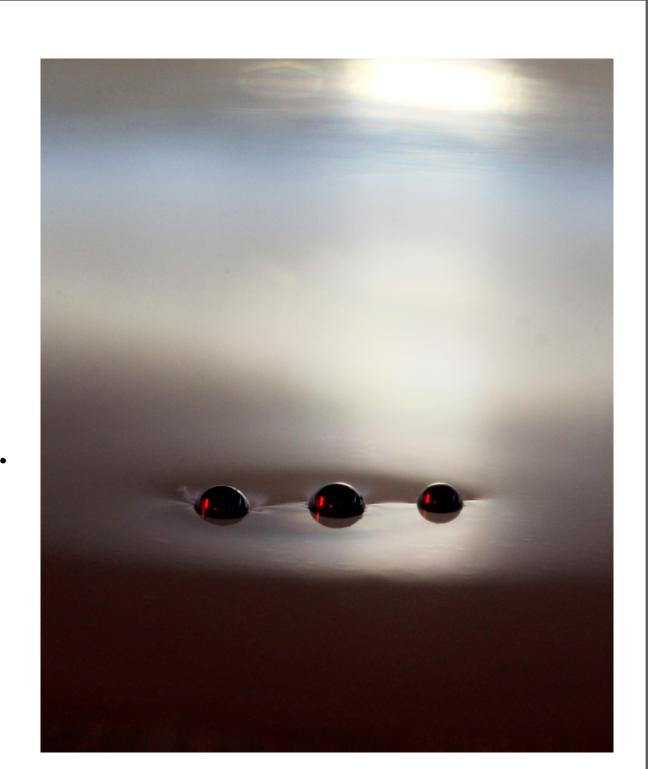


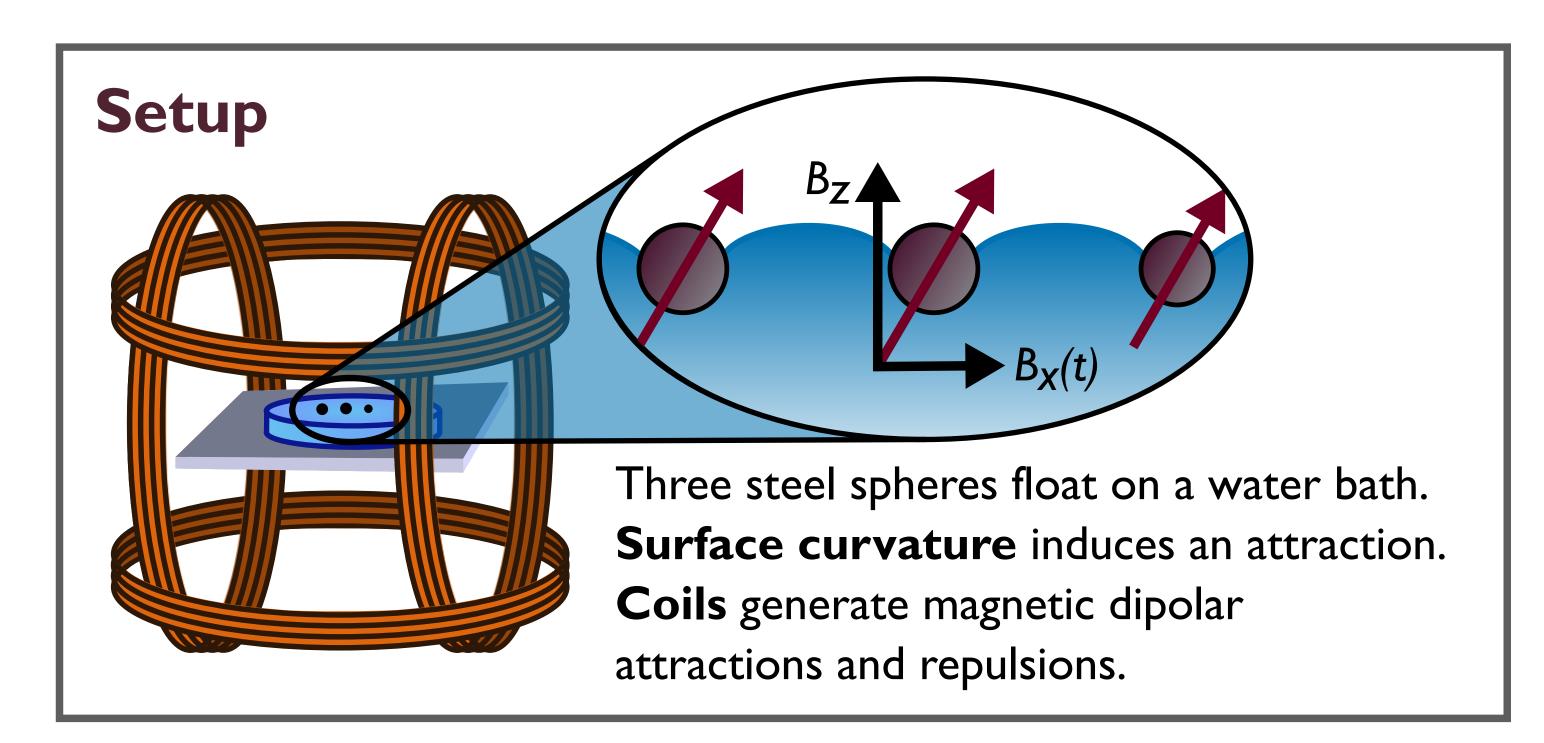
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Microswimmer

Simple microswimmers are created using floating steel spheres.

Magnetic and capillary interactions cause the particles to self-assemble. Magnetic oscillations generate motion. Three in-line spheres behave like the Najafi-Golestanian swimmer [1]. Speed is proportional to the cycle described by the two elongations. A spring model gives predictions.

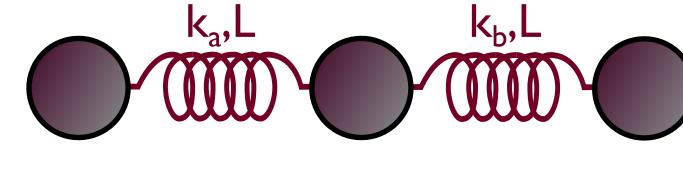




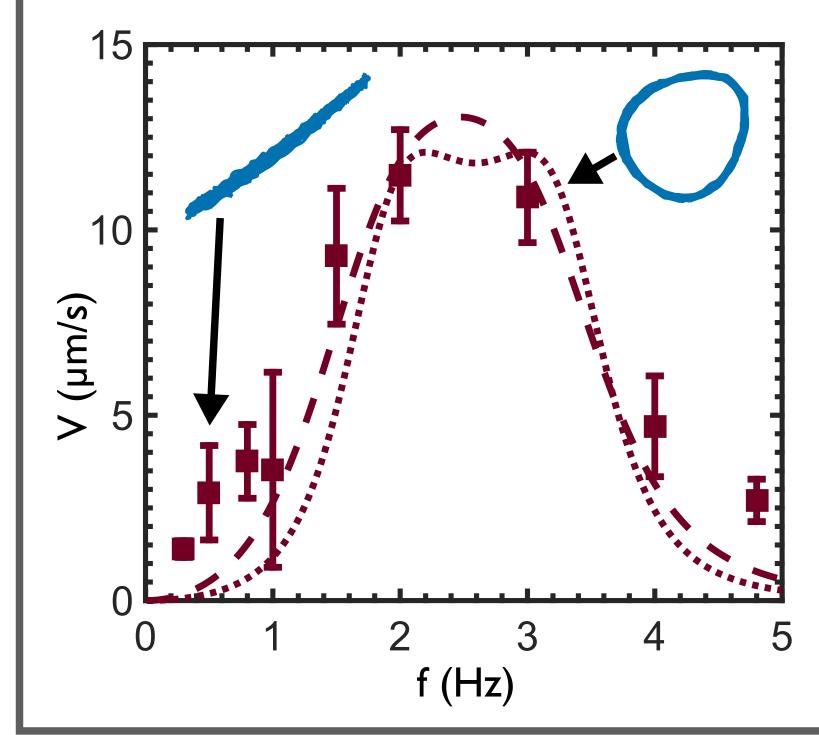
Results and model

A sinusoidal field $B_X(t)$ generates deformations and motion.

The magnetocapillary interaction acts as a **spring force** [2]. Using spheres of different sizes



allows to have different spring constants.



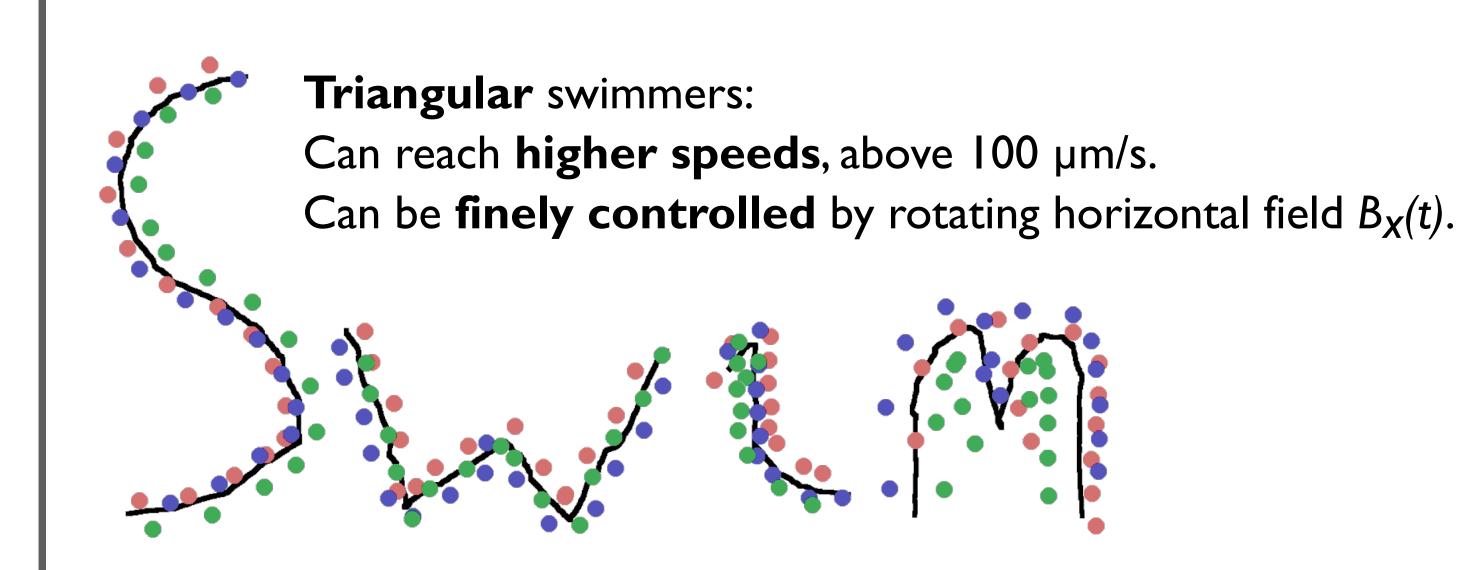
Speed is maximal close to the spring's resonance. It is proportional to the area enclosed in the trajectory described by the elongations. A linear spring model predicts the speed profile accurately, analytically, and with no adjustable parameter [1].

Micromanipulator

Different kinds of structures can be built for **different purposes**. **Triangular** swimmers are **faster** (~100 µm/s) and **controllable** [3]. **Larger** swimmers can **transport cargo**.

Rotating swimmers generate local mixing at low Reynolds number.

Remote-control

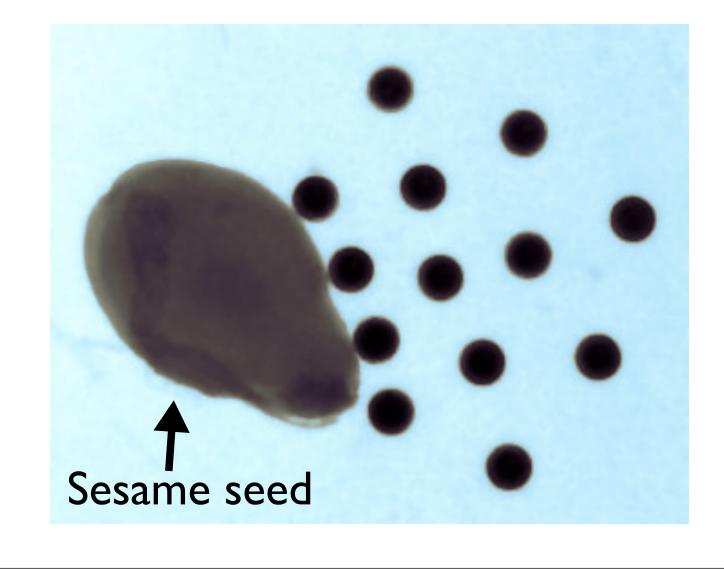


Cargo transport

Floating objects are captured through capillary interaction.

Transport can be achieved.

The cargo can be released using a magnetic field gradient.

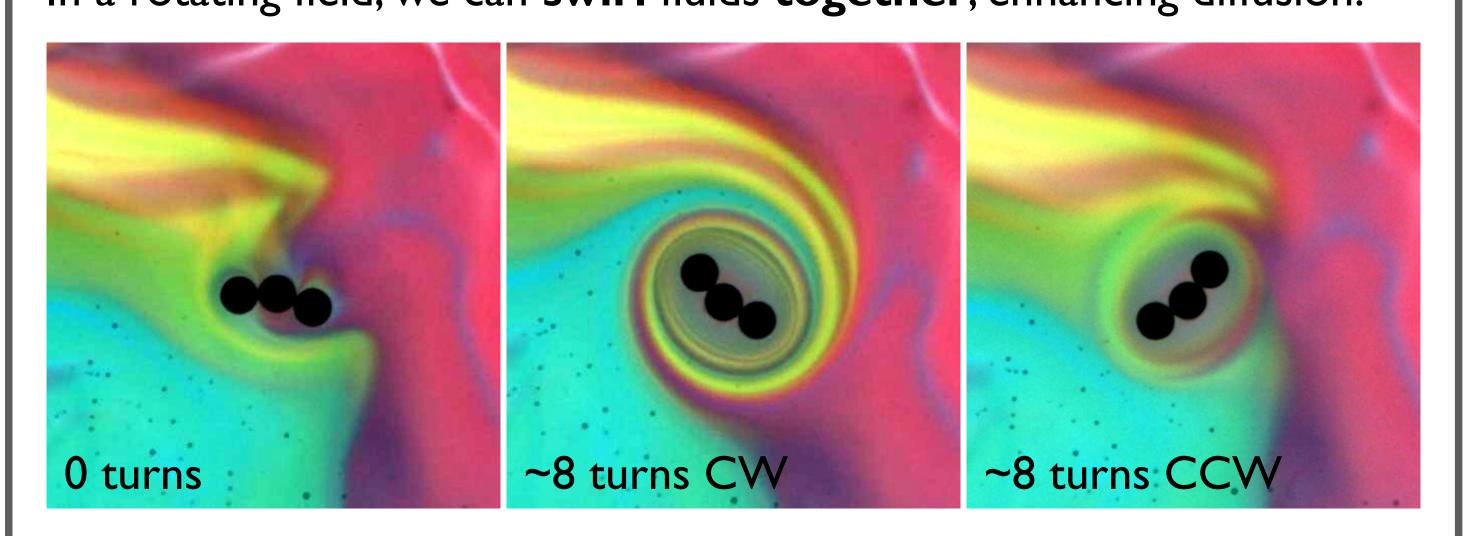


Mixing

Micromixing relies on **diffusion** instead of convection.

The goal is to **maximize** the contact **area** between the fluids.

In a rotating field, we can **swirl** fluids **together**, enhancing diffusion.



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References

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